第一图书网, tushu007.com << 复杂系统暨鲁棒控制的理论和应用>>

图书基本信息

书名: <<复杂系统暨鲁棒控制的理论和应用>>

- 13位ISBN编号:9787302234869
- 10位ISBN编号:7302234868
- 出版时间:2010-8
- 出版时间:清华大学出版社
- 作者:黄杰,刘康志,(日)太田快人 编著
- 页数:285

版权说明:本站所提供下载的PDF图书仅提供预览和简介,请支持正版图书。

更多资源请访问:http://www.tushu007.com



内容概要

the japan-china joint workshop on control was initiated in the august of 2004. the first and second joint workshops were held in beijing and harbin of china, respectively. the third joint workshop moved to japan and was held on the 18th of august, 2009 in fukuoka international conference center, as a part of sice annual conference of 2009. the third joint workshop was co-sponsored by the control division of society of instrument and control engineers, japan (sice) and the technical committee on control theory of chinese association of automation, china (caa).

this joint workshop provides a forum for the scientists and engineers from both japan and china, who are active in the field of control engineering, to present their most recent research outcomes and to exchange as well as to share their visions, ideas on control engineering. the focus of the third joint workshop is on complex systems and robust control. we are privileged that many world famous scholars from both sides took part in this workshop and delivered four keynote speeches. after a full day active discussion, all participants felt that the presentations in the workshop were both interesting and inspiring. the publication of a book of selected papers from this joint workshop will undoubtedly contribute to the control community of the world. so, the steering committee decided to publish this book.

this book is organized as two parts: one on complex systems and another on robust control.



作者简介

作者:黄杰刘康志(日本)太田快人

第一图书网, tushu007.com << 复杂系统暨鲁棒控制的理论和应用>>

书籍目录

part i theory and applications of complex systems towards a common principle of biological control -- how control weaves the string of life hidenori kimural, shingo shimoda1, lu gaohuai and reiko j. tanaka2 target localization and tracking with motion sensors daizhan chengx, bijoy k. ghosh2 and xiaoming hus network failure locating via end-to-end verification daizhan cheng1 and yutaka takahashi2 an algebraic solution method of the hamilton-jacobi equation toshiyuki ohtsuka stochastic optimal control for a class of manufacturing systems based on event-based optimization yanjia zhao, gianchuan zhao and xiaohong guan computing frequency response gain of controlled spatio-temporal systems hisaya fujioka stability analysis of adrc for nonlinear systems with unknown dynamics and disturbances wenchao xue and yi huang nonlinear output feedback control for saturated systems and its application daisuke akasaka and kang-zhi liu estimation of liss properties via a quadratic form liss-lyapunov function shengyu wu and shengwei mei torque balancing for multi-cylinder si engines and its experimental validation po li and tielong shen experimental validation of robustness of individual air-fuel ratio control algorithms yinhua liu1, tielong shen1, di lu2, kenji suzuki3 and kota sara3 on energy-based control for underactuated mechanical systems xin xin passivity based bilateral control for double-screw-drive forceps teleoperation system with constant time delay chiharu ishiil, kosuke kobayashi2, yusuke kamei3, yosuke nishitani4 and hiroshi hashimoto5 identification of respiratory system considering hysteresis of pulmonary elastance shunshoku kanae1, zi-jiang yang2 and kiyoshi wada3 part ii theory and applications of robust control neo-robust control theory -- beyond the small-gain and passivity paradigms



kang-zhi liu robust output feedback control of hagc system in gold strip mill with delayed measurement xin li, xiaohong jiao and xiaofei liu a robust adaptive ha control method for robot manipulators with input nonlinearities kazuya sato1, takanori nakashima1 and kazuhiro tsuruta2 delay-dependent robust stability criteria for systems with interval time-varying delay tao zhang and guokai xu output feedback h control combining moving horizon scheme for active suspension based on Imi juan wang and haiying du

第一图书网, tushu007.com << 复杂系统暨鲁棒控制的理论和应用>>

章节摘录

版权页:插图:2 Control as a transdisciplinary principle Control engineering was born at almost the same time as modern technol- ogy was born in the era of Industrial Revolution . So , it is one of the oldest disciplines of engineering, which is consistent with saying "no machine works without control". Since then, control engineering has been developed in pace with the progress of modern technology and now it reaches a certain level of maturity on which contemporary technology seriously depends, as we notice. A salient characteristic feature of control engineering lies in its universality in the sense that it is used commonly in almost all areas of engineering . En-gineering disciplines are divided into several categories based on the types of energy resources they use ; electrical, mechanical, chemical and SO on. Control engineering is out of this categorization. It is used indispensably in these fields and sometimes embedded naturally in these disciplines. We find many other such disciplines, apart from control engineering, namely, systems engineering, network engineering, optimization , design engineering , human / machine inter- face , reliability engineering , and SO on . Now , it is natural to divide engineering disciplines into two categories : The one includes those engineering based es- sentially on the natural sciences whose objectives are to exploit the potentials of Nature for the use of human being, and the other includes those that do not directly related to the Nature, rather related to the artifacts, society and humans. The disciplines included in the former category tend to concentrate on refining each component of systems and promote each specific technology, SO that further ramifications take place . On the other hand, the disciplines in the latter category tend to integrate different disciplines to challenge the problems. We may call the engineering fields contained in the first category applied engineering, while those in the second category pure engineering . The names come from the fact that the disciplines in the first category are essentially regarded as applications of natural sciences, while those in the second category are independent from natural science and are closed within the engineering world.



编辑推荐

《复杂系统暨鲁棒控制的理论和应用》由清华大学出版社出版。



版权说明

本站所提供下载的PDF图书仅提供预览和简介,请支持正版图书。

更多资源请访问:http://www.tushu007.com