<<现代动力系统理论导论>>

图书基本信息

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内容概要

this book provides the first self-contained comprehensive exposition of the theory of dynamical systems as a core mathematical discipline closely intertwined with most of the main areas of mathematics. the authors introduce and rigorously develop the theory while providing researchers interested in applications with fundamental tools and paradigms.

the book begins with a discussion of several elementary but fundamental examples, these are used to formulate a program for the general study of asymptotic properties and to introduce the principal theoretical concepts and methods, the main theme of the second part of the book is the interplay between local analysis near individual orbits and the global complexity of the orbit structure, the third and fourth parts develop in depth the theories of !ow-dimensional dynamical systems and hyperbolic dynamical systems.

the book is aimed at students and researchers in mathematics at all levels from ad-vanced undergraduate up. scientists and engineers working in applied dynamics, non-linear science, and chaos will also find many fresh insights in this concrete and clear presentation. it contains more than four hundred systematic exercises.

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作者简介

编者:(美国)卡托克(Katok A.)

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书籍目录

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- 2. flows, vector fields, differential equations
- 3. time-one map, section, suspension
- 4. linearization and localization

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- 9. symbolic dynamical systems

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.perron-frobenius operator for positive matrices

- 2. equivalence, classification, and invariants
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- 2. smooth conjugacy and time change for flows
- 3. topological conjugacy, factors, and structural stability
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- 5. coding, horseshoes, and markov partitions
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- 6. stability of hyperbolic total automorphisms
- 7. the fast-converging iteration method (newton method) for the

conjugacy problem

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- 8. the poincare-siegel theorem
- 9. cocycles and cohomological equations
- 3. principalclassesofasymptotictopologicalinvariants
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- 4.statistical behavior of orbits and introduction to ergodic theory
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7. algebraic dynamics: homogeneous and afline systems part 2local analysis and orbit growth

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- 2. genericity of systems with hyperbolic periodic points transverse fixed points; the kupka-smale theorem
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for smooth maps; the topological definition of degree

- 3. degree and topological entropy
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- 7. nielsen theory and periodic points for toral maps
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- 2. the billiard problem
- 3. twist maps

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- 3. action functionals, minimal and ordered orbits minimal action; minimal orbits; average action and minimal measures; stable sets for aubry-mather sets
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- 7. geodesic flows on rank-one symmetric spaces
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- 6. multiplicative asymptotic for growth of periodic points local product flow boxes; the multiplicative asymptotic of orbit growth supplement
- s. dynamical systems with nonuniformly hyperbolic behavior byanatolekatokandleonardomendoza
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- 2. Iyapunov exponents cocycles over dynamical systems; examples of cocycles; the multiplicative ergodic theorem; osedelec-pesin e-reduction theorem; the rue!!e inequality
- 3. regular neighborhoods existence of regular neighborhoods; hyperbolic points, admissible manifolds, and the graph transform
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 pseudo-markov covers; the livschitz theorem
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 measures and transverse homoclinic points; the spectral
 decomposition theorem; entropy,horseshoes, and periodic points for
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- 2. functional analysis
- 3. differentiable manifolds differentiable manifolds; tensor bundles; exterior calculus; transversality
- 4. differential geometry
- 5. topology and geometry of surfaces
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章节摘录

版权页:插图:The purpose of tlus chapter is to introduce the variational approach to dy-namics, that is, to show how interesting orbits in some dynamical systemscan be found as special critical points of functionals defined on appropriateauxiliary spaces of potential orbits. This idea goes back to the variational prin-ciples in dassical mechanics (Maupertuis, d'Alembert, Lagrange, etc.) . rfheclassical continuous-time case presents certain difficulties related to infinite-dimensionality of the spaces of potential orbits. In order to demonstrate theessential features of this approach and to avoid those difficulties we start in Section 2 with a model geometric problem describing the motion of a pointmass inside a convex domain. Then we consider in Section 3 a more generalclass of area-preserving two-dimensional dynamical systems, twist maps, which possesses the essential features of that example, but covers many other inter-esting situations. The main result there is Theorem 9.3.7, which guarantees existence of in, fin, itely 'many periodic orbits with a special behavior for any twist map. At least as important as that result itself is the machinery involving theaction functional (9.3.7) for the periodic problem, which will be extended in Chapter 13 to give results about nonperiodic orbits. Furthermore, after de-veloping the necessary local theory, the approach can then be refined to studycontinuous-time systems as well, although we only carry out the program forgeodesic flows, where the action functional has a particularly clear geometricinterpretation. An important ingredient here is to reduce the global problem to a finite-dimensional one by considering "broken geodesics" (cf. the proof of Theorem 9.5.8). We concentrate our attention in Sections 6 and 7 on describing the invariant set consisting of globally minimal geodesics, that is, geodesics which on the universal cover are length-minimizing segments between any two of their points. There are two principal conclusions: Theorem 9.6.7 connects the geometrical complexity of the manifold measured by the growth of the volume of balls on the universal cover with the dynamical complexity of the geodesic flow measured by the topological entropy.

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